

61 Linear Algebra Review

2.1.

$$\bar{x} \in \mathbb{R}^n \text{ or } \bar{x} \in \mathbb{C}^n$$

$$\bar{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, \quad x_i \in \mathbb{R} \text{ or } \mathbb{C}$$

Def. 1.1 $L: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is linear if

$$L(\alpha \bar{v} + \beta \bar{w}) = \alpha L(\bar{v}) + \beta L(\bar{w})$$

all $\alpha, \beta \in \mathbb{R}$ and all $\bar{v}, \bar{w} \in \mathbb{R}^n$.

$$L(\mathbf{0}) = \mathbf{0}$$

Let $\bar{e}_i = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \leftarrow i^{\text{th}} \text{ coord.} = 1.$ Standard
basis
vectors

$$\text{Then } \bar{x} = \sum_{i=1}^n x_i \bar{e}_i.$$

Call A be a matrix

$$(a_{ij}) = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$$

of dim. $n \times n$.

62

$$A\bar{x} = \begin{pmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1m}x_m \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2m}x_m \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mm}x_m \end{pmatrix}$$

If $L(\bar{e}_i) = \bar{v}_i$ and

$$A = \begin{pmatrix} \vdots & \vdots & \dots & \vdots \\ \bar{v}_1 & \bar{v}_2 & \dots & \bar{v}_m \\ \vdots & \vdots & \dots & \vdots \end{pmatrix} \quad \begin{pmatrix} \bar{v}_i \\ \text{column vectors} \\ \text{in } A \end{pmatrix}$$

then

$$L(\bar{x}) = A\bar{x}$$

matrix representation
of L (in standard
basis)

Pf. $L(\bar{x})$

$$= L\left(\sum_{i=1}^m \bar{e}_i x_i\right) \underset{\text{lin.}}{=} \sum_{i=1}^m x_i L(\bar{e}_i)$$

$$= \sum_{i=1}^m x_i \bar{v}_i$$

$$\begin{aligned} (L\bar{x})_j &= \sum_{i=1}^m x_i (\bar{v}_i)_j = x_1(\bar{v}_1)_j + x_2(\bar{v}_2)_j + \dots + x_m(\bar{v}_m)_j \\ &= a_{j1}x_1 + a_{j2}x_2 + \dots + a_{jm}x_m \\ &= (A\bar{x})_j \end{aligned}$$

63

Prop 1.4. Let L and P be linear maps with matrix repr. A and B , respectively. Then

$$(P \circ L)(\vec{v}) = (BA)\vec{v}, \quad \vec{v} \in \mathbb{R}^n$$

↑
function composition

↑
matrix mult.

$$I_n \stackrel{\text{not.}}{=} \begin{bmatrix} 1 & 0 & & 0 \\ 0 & 1 & & \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & & 1 \end{bmatrix}$$

$n \times n$ identity matrix

L is invertible iff L is bijective from \mathbb{R}^n to \mathbb{R}^n

iff its matrix repr. A has an inverse B (i.e., $BA = AB = I_n$). Not.: A^{-1} .

Note: A is invertible $\Leftrightarrow \det(A) \neq 0$.

Def. 1.5 L_1 and L_2 linear. They are linearly conjugate if there is a linear P such that

$$P \circ L_1 = L_2 \circ P$$

(invertible)

or
$$L_1 = P^{-1} \circ L_2 \circ P$$

64 If $L_1(\bar{x}) = A_1 \bar{x}$, $L_2(\bar{x}) = A_2 \bar{x}$ and $P(\bar{x}) = G\bar{x}$,
 where A_1, A_2, G are $n \times n$ matrices, then

$$G A_1 = A_2 G \quad \text{or} \quad A_1 = G^{-1} A_2 G$$

We say that the matrices A_1 and A_2 are
similar.

Def. 1.6 A $n \times n$ matrix. $\lambda \in \mathbb{C}$ is an
eigenvalue of A if it is a ^{zero} root of
 the characteristic polynomial $p(\lambda)$
 of A . $p(\lambda) = \det(A - \lambda I)$

An eigenvector \bar{v} associated with λ is
 a vector $\neq \bar{0}$ such that

$$A \bar{v} = \lambda \bar{v}$$

algebraic
 The multiplicity of λ is its multiplicity
 as a root of $p(\lambda)$.
 or zero

Note If $A: \mathbb{R}^m \rightarrow \mathbb{R}^m$ then it may be
 extended to $A: \mathbb{C}^m \rightarrow \mathbb{C}^m$ by defining

$$A(i\bar{y}) = i A\bar{y}$$

The eigenvector may be complex!
 & eigenvalue

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65 For A real, $p(\lambda)$ is a real n^{th} degree polynomial. So if λ is a zero then $\bar{\lambda}$ is one, too.

Ex. $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ has eigenvalues $\pm i$

The eigenvector corresp to i is any multiple $\neq 0$ of $\begin{pmatrix} 1 \\ i \end{pmatrix}$.

Prop 1.9 If $L_1(\bar{x}) = A_1 \bar{x}$ and $L_2(\bar{x}) = A_2 \bar{x}$ are linearly conjugate, then A_1 and A_2 have the same eigenvalues.

$$\begin{aligned}
 \text{Pf. } \det(A_1 - \lambda I) &= \det(G^{-1} A_2 G - \lambda I) \\
 &= \det(G^{-1} A_2 G - G^{-1} \lambda G) \\
 &= \det(G^{-1} (A_2 - \lambda I) G) \\
 &= \det G^{-1} \cdot \det(A_2 - \lambda I) \cdot \det G \\
 &= \underbrace{\det G^{-1}}_{(\det G)^{-1}} \cdot \det(A_2 - \lambda I) \\
 &= \det(A_2 - \lambda I)
 \end{aligned}$$

66 Theorem 1.10 Let $L: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

be linear with $L(\bar{x}) = A\bar{x}$. There exists a real, 3×3 matrix G such that $G^{-1}AG$ is invertible

takes one of the four forms

$$1. \begin{pmatrix} \alpha & -\beta & 0 \\ \beta & \alpha & 0 \\ 0 & 0 & \lambda \end{pmatrix}$$

$$2. \begin{pmatrix} \lambda & 0 & 0 \\ 0 & \mu & 0 \\ 0 & 0 & \eta \end{pmatrix}$$

$$3. \begin{pmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \mu \end{pmatrix}$$

$$4. \begin{pmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{pmatrix}$$

where all entries are real, $\beta \neq 0$,
and

called: standard forms.

Cor 1.11 Let A be 2×2 real. Then there exists a real invertible 2×2 matrix G such that $G^{-1}AG$ is of one of the forms

1.
$$\begin{pmatrix} \alpha & -\beta \\ \beta & \alpha \end{pmatrix}$$

2.
$$\begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$$

3.
$$\begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix}$$

Proof of the 2×2 case

First, let A have complex eigenvalues

$$\lambda_+ = \alpha + i\beta, \quad \lambda_- = \alpha - i\beta.$$

Let \bar{w} be the eigenvector associated with $\alpha + i\beta$. Write $\bar{w} = \bar{v}_1 + i\bar{v}_2$, \bar{v}_i real 2-dim. vectors.

Since $A\bar{w} = (\alpha + i\beta)\bar{w} = (\alpha + i\beta)(\bar{v}_1 + i\bar{v}_2)$
 $= \alpha\bar{v}_1 - \beta\bar{v}_2 + i(\beta\bar{v}_1 + \alpha\bar{v}_2)$

$$\begin{aligned} A\bar{v}_1 &= \alpha\bar{v}_1 - \beta\bar{v}_2 \\ A\bar{v}_2 &= \beta\bar{v}_1 + \alpha\bar{v}_2 \end{aligned}$$

\bar{v}_1, \bar{v}_2 lin. indep.

68 $G = \begin{pmatrix} \bar{v}_1 & \bar{v}_2 \end{pmatrix}$ is invertible since \bar{v}_1, \bar{v}_2 lin. indep.

Check

$$G \begin{pmatrix} \alpha & +\beta \\ -\beta & \alpha \end{pmatrix} = AG$$

$$\begin{pmatrix} (\bar{v}_1)_1 & (\bar{v}_2)_1 \\ (\bar{v}_1)_2 & (\bar{v}_2)_2 \end{pmatrix} \begin{pmatrix} \alpha & +\beta \\ -\beta & \alpha \end{pmatrix} = \begin{pmatrix} (\bar{v}_1)_1 \alpha - (\bar{v}_2)_1 \beta & +(\bar{v}_1)_1 \beta + (\bar{v}_2)_1 \alpha \\ (\bar{v}_1)_2 \alpha - (\bar{v}_2)_2 \beta & +(\bar{v}_1)_2 \beta + (\bar{v}_2)_2 \alpha \end{pmatrix}$$

$$AG = \begin{pmatrix} A\bar{v}_1 & A\bar{v}_2 \end{pmatrix} = \begin{pmatrix} (\bar{v}_1)_1 \alpha - (\bar{v}_2)_1 \beta & (\bar{v}_1)_1 \beta + (\bar{v}_2)_1 \alpha \\ (\bar{v}_1)_2 \alpha - (\bar{v}_2)_2 \beta & (\bar{v}_1)_2 \beta + (\bar{v}_2)_2 \alpha \end{pmatrix}$$

Secondly, if one eigenvalue λ is real then so is the other μ .

If $\lambda = \mu$ we can have

$$(A - \lambda I)^2 \bar{v} = 0$$

for a $\bar{v} \neq 0$ but

cf. 68a

CASE 2.

$$(*) \quad (A - \lambda I) \bar{v} \neq 0$$

Take $\bar{w}_1 = \bar{v}$ and $(A - \lambda I) \bar{w}_1 = \bar{w}_2$. Then

$$A \bar{w}_2 = \lambda \bar{w}_2 \quad (\text{because } (A - \lambda I)^2 \bar{w}_1 = 0)$$

$$A \bar{w}_1 = \lambda \bar{w}_1 + \bar{w}_2 \quad (\text{def. of } \bar{w}_2)$$

\bar{w}_1, \bar{w}_2 lin. indep.

Check again that $G = \begin{pmatrix} \bar{w}_2 & \bar{w}_1 \end{pmatrix}$ works.

If, in the preceding (*), $(A - \lambda I) \bar{v} = 0$ for all \bar{v} , then the nullspace of $A - \lambda I$ is two-dim.