

Quadratic Optimal Control through Spectral and Coprime Factorization

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Keywords: Wiener-Hopf Factorization, Spectral Factorization, Input delay, Transmission line.

We study the infinite horizon quadratic cost minimization problem for a linear time-invariant distributed parameter system with finitely many inputs and outputs. We work in an input/output framework, and reduce the unstable case to the stable case by the use of a right coprime factorization of the impulse response and a preliminary stabilizing feedback. The stable case is then solved through spectral factorization. The theory is illustrated with two examples involving pure time delays.