Weak admissibility does not imply admissibility for analytic semigroups

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Abstract

Two conjectures on admissible control operators by George Weiss are disproved in this paper. One conjecture says that an operator $B$ defined on an infinite-dimensional Hilbert space $U$ is an admissible control operator if for every element $u \in U$ the vector $Bu$ defines an admissible control operator. The other conjecture says that $B$ is an admissible control operator if a certain resolvent estimate is satisfied. The examples given in this paper show that even for analytic semigroups the conjectures do not hold. In the last section we construct a semigroup example showing that the first estimate in the Hille–Yosida theorem is not sufficient to conclude boundedness of the semigroup.

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1. Introduction

It is well-known that homogeneous linear partial differential equations can be written as abstract differential equations on a Banach or Hilbert space. For instance, the diffusion equation in a metal bar of length one,

$$\frac{\partial}{\partial t}w(t, \xi) = \frac{\partial^2}{\partial \xi^2} w(t, \xi), \quad t \geq 0, \quad \xi \in (0, 1),$$

with boundary conditions

$$\frac{\partial}{\partial \xi} w(t, 0) = \frac{\partial}{\partial \xi} w(t, 1) = 0$$

can be written as the abstract differential equation

$$\dot{x}(t) = Ax(t),$$

where $x(t)$ denotes the temperature profile at time $t$, i.e., $w(t, \cdot)$. This temperature profile is assumed to be an element of $L^2(0, 1)$. Furthermore, $A$ is a linear operator from its domain $D(A)$ to $L^2(0, 1)$ defined as

$$Ah = \frac{d^2h}{d\xi^2},$$

on

$$D(A) = \left\{ h \in L^2(0, 1) \right| \frac{d^2h}{d\xi^2} \in L^2(0, 1) \right\}$$

with $\frac{dh}{d\xi}(0) = \frac{dh}{d\xi}(1) = 0$.

A homogeneous linear partial differential equation (p.d.e.) has for every initial condition a unique (weak)
solution which depends continuously on the initial condition if and only if the operator $A$ appearing in the corresponding abstract differential equation generates a $C_0$-semigroup, which we denote by $T(\cdot)$. For the partial differential equation (1) with boundary conditions (2) this is the case. Furthermore, $T(t)w(0, \cdot) = x(t)$ in $L^2(0, 1)$ for all $t \geq 0$. For more detail, see [2, Chapter 2].

The Hille–Yosida theorem gives necessary and sufficient conditions for an operator $A$ to generate a $C_0$-semigroup. Hence, this theorem can be used to determine whether the p.d.e. has a unique solution on a Hilbert space. We wonder if $A$ is bounded. In order to see this from properties of the operators $A$ and $B$, we introduce again $x(t)$ as the temperature profile at time $t$, we can rewrite (1) and (4) as (see [13])

$$
\dot{x}(t) = Ax(t) + Bu(t), \quad x(0) = x_0, \quad t \geq 0,
$$

(5)

where $A$ is the same as in (3) and $B$ is given as

$$
B = \delta,
$$

(6)

where $\delta$ is the delta distribution at $\xi = 0$. Hence, we see that $B$ does not lie in $L^2(0, 1)$, and thus does not define an operator from $C$ to $L^2(0, 1)$. Since $L^2(0, 1)$ is the space in which we want that the state $x(t)$ takes its values, it is not directly clear if every input function $u$ is such that the solution $x$ of (5) lies in $L^2(0, 1)$. As in the Hille–Yosida theorem, we would like to conclude this from properties of the operators $A$ and $B$.

We consider the abstract differential equation

$$
\dot{x}(t) = Ax(t) + Bu(t), \quad x(0) = x_0, \quad t \geq 0
$$

(7)
on a Hilbert space $H$ with $x_0 \in H$ and with $u$ in some space of functions taking values in a Hilbert space $U$. We denote this class of inputs by $\mathcal{U}$. We wonder if for any input $u \in \mathcal{U}$ and any initial condition $x_0$ there exists a unique solution $x$ with values in $H$ satisfying (weakly) Eq. (7). Choosing $u = 0$, we see that $A$ has to generate a $C_0$-semigroup $T(\cdot)$ on $H$. The answer to the earlier question depends on the class $\mathcal{U}$ of input functions. If $u$ is very smooth, then it is more likely that (7) has a solution than if $u$ is merely $L^1$. Throughout this paper we take $\mathcal{U}$ to be $L^2_{loc}(0, \infty; U)$. This choice of input functions is motivated by the fact that this is the space which is normally used in control theory.

Weiss [17] showed that if the solution of (7) takes its values in $H$ for any $u \in L^2_{loc}(0, \infty; U)$, then $B \in \mathcal{L}(U, D(A^*'))$, where $D(A^*)$ is the domain of the adjoint of $A$, and $'$ denotes the dual space. $D(A^*')$ can also be seen as the completion of $H$ with respect to the norm

$$
\|x\|_{D(A^*')} = \|(\lambda I - A)^{-1}x\|_H,
$$

where $\lambda$ is an arbitrary point in the resolvent set of $A$. Note that this implies that $B$ is a bounded operator from $U$ to $H$ whenever $A$ is a bounded operator on $H$ (usually $A$ is unbounded).

Since the $C_0$-semigroup $T(\cdot)$ can be extended to $D(A^*)'$, we can consider (7) as an abstract differential equation on this larger Hilbert space. As an operator from $U$ to $D(A^*)'$, the control operator $B$ is bounded and thus the solution (7) is given by

$$
x(t) = T(t)x_0 + \int_0^t T(t - \rho)Bu(\rho) \, d\rho.
$$

(8)

Since $x_0$ is an element of $H$, it is clear that $x(t)$ lies in $H$ if and only if the integral term lies in $H$ for every $u$. Operators $B$ for which the integral term lies in $H$ for every $u$ are called admissible.

**Definition 1.1.** $B \in \mathcal{L}(U, D(A^*))$ is called an admissible control operator for $T(\cdot)$ if, for some $t > 0$,

$$
\int_0^t T(t - \rho)Bu(\rho) \, d\rho \in H
$$

(9)

for all $u \in L^2(0, t; U)$. $B \in \mathcal{L}(U, D(A^*))$ is a weakly admissible control operator for $T(\cdot)$, i.e., (9) holds for all $u$ of the form $u(\rho) = vw(\rho)$, where $v \in U$ and $w \in L^2(0, t; \mathbb{C})$.

Using the semigroup property of $T(\cdot)$, it is not hard to see that (9) is satisfied for every $t > 0$ if it is satisfied for some $t > 0$. 

It follows from the closed graph theorem that if $B$ is an admissible control operator for $T(\cdot)$ then, for each $t > 0$, there exists a constant $M_t > 0$ such that

$$\left\| \int_0^t T(t - \rho)Bu(\rho)\,d\rho \right\|_H \leq M_t \|u\|_{L^2(0,t;U)},$$

$$u \in L^2(0,t;U).$$

(10)

Thus, an inhomogeneous linear partial differential equation of type (7) has for every initial condition and every locally square integrable input a unique (weak) solution which depends continuously on the initial condition and the input if and only if the operator $A$ generates a $C_0$-semigroup $T(\cdot)$ and $B$ is an admissible control operator for $T(\cdot)$.

For p.d.e.’s special techniques for solving the admissibility problem are available, see for example [9]. If the operator $A$ has a Riesz basis of eigenvectors and $U = \mathbb{C}$, then it has been proved that admissibility of $B$ is equivalent to the fact that a certain measure is a Carleson measure, see [7,16]. All these results apply only to specific cases.

Weiss [18] conjectured the following simple condition for the admissibility of $B$.

**Conjecture 1.2.** Let $B \in \mathcal{L}(U,D(A^{\ast}\')$. Then $B$ is an admissible control operator for $T(\cdot)$ if and only if $B$ is a weakly admissible control operator for $T(\cdot)$.

Clearly, admissibility implies weak admissibility. For left-invertible $C_0$-semigroups Weiss [18] showed that also the converse is true, i.e., the conjecture holds for such semigroups. This implication has also been proved for normal analytic semigroups, see [6]. Here we show that this implication no longer holds for compact analytic semigroups, see Example 2.3. It is a little bit surprising that the conjecture does not hold for analytic semigroups, since they satisfy $T(t)B \in \mathcal{L}(U,H)$ for all $t > 0$. Recently, Le Merdy [11] showed that Conjecture 1.2 holds for an analytic semigroup if and only if $A^{1/2}$ is admissible.

Let $\omega$ denote the growth bound of $T(\cdot)$. Taking $u(t)=e^{-\omega t}u_0$ with $u_0 \in U$ and $\text{Re}(s) > \max\{0,\omega+1\}$, and using (10) we see that admissibility implies $\|(sI-A)^{-1}B\| \leq M/\sqrt{\text{Re}(s)}$. In Weiss [18] the following conjecture appeared.

**Conjecture 1.3.** Let $B \in \mathcal{L}(U,D(A^{\ast}\')$. Then the following statements are equivalent:

1. $B$ is an admissible control operator for $T(\cdot)$.
2. There exist constants $K, \omega > 0$ such that

$$\|(sI-A)^{-1}B\| \leq \frac{K}{\sqrt{\text{Re}(s)}}, \quad s \in \mathbb{C}, \quad \text{Re}(s) > \omega.$$  

(11)

It is known [6] that this conjecture is also true for left-invertible semigroups, as well as for normal analytic ones. Furthermore, from the recent work of Le Merdy [11] we know that Conjecture 1.3 holds if and only if it holds for $B = A^{1/2}$. Since Weiss [18] showed that Conjecture 1.3 implies Conjecture 1.2, we have disproved Conjecture 1.3 as well. We also show that our example from Section 2 satisfies the stronger necessary condition for admissibility given in Staffans [15, Section 4.2], namely,

$$\|(sI-A)^{-n}B\| \leq M \frac{1}{n^{1/4} \text{Re}(s)^{n-1/2}},$$

$$n \in \mathbb{N}, \quad s \in \mathbb{C}, \quad \text{Re}(s) > \omega.$$  

(12)

A necessary and sufficient condition for admissibility was obtained by Grabowski and Callier [5]. They showed that $B$ is an admissible control operator for $T(\cdot)$ if and only if there exist positive $M$ and $\omega$ such

$$\sum_{k=0}^{n-1} \frac{e^{-s\cdot(\cdot)}(\cdot)^k}{k!} B^*(sI-A)^{-n-k}x_0 \leq M \frac{\|x_0\|}{\text{Re}(s)^n},$$

(13)

for all $n \in \mathbb{N}$, $x_0 \in H$, and all $s$ with $\text{Re}(s) > \omega$. However, this condition is very hard to check. We remark that since this condition was obtained via the Hille–Yosida theorem, it is sufficient to check (13) for real $s$ only.

If we study the limit behavior of solutions of (7), a stronger concept than admissibility is needed, called infinite-time admissibility.

**Definition 1.4.** $B \in \mathcal{L}(U,D(A^{\ast}\')$ is called an infinite-time admissible control operator for $T(\cdot)$, if there
exists a constant $M > 0$ such that

$$
\left\| \int_0^\infty T(\rho)Bu(\rho) \, d\rho \right\|_H \leq M \|u\|_{L^2(0, \infty; U)}.
$$

For all $s$ with $\text{Re}(s) > 0$, then the semigroup is exponentially stable (see [15, Lemma 3.11.7]).

2. Weak admissibility does not imply admissibility

Throughout this paper $H$ is a separable Hilbert space. All our examples are based on the fact that it is possible to find a normalized basis $\{\varphi_n\}_{n \in \mathbb{N}}$ in $H$ which is not Hilbertian. By a basis we mean a sequence $\{\varphi_n\}_{n \in \mathbb{N}}$ such that for every $x \in H$ there exists a unique sequence of scalar coefficients $\{f_n\}_{n \in \mathbb{N}}$, such that

$$
x = \sum_{n=1}^\infty f_n \varphi_n := \lim_{N \to \infty} \sum_{n=1}^N f_n \varphi_n.
$$

This basis is normalized if $\|\varphi_n\| = 1$ for all $n \in \mathbb{N}$. Such bases are studied in great detail in Singer [14]. A basis $\{\varphi_n\}_{n \in \mathbb{N}}$ is Hilbertian if there is a constant $C$ such that for all $N \in \mathbb{N}$ and all scalar sequences $\{f_n\}_{n=1}^N$ we have

$$
\left\| \sum_{n=1}^N f_n \varphi_n \right\|^2 \leq C \sum_{n=1}^N |f_n|^2.
$$

The semigroups that we construct and their generators will be diagonal operators with respect to some basis. Such operators have been studied by several people. The following result is well-known, and a proof can be found in e.g. [1, Lemma 3.2.5].

Lemma 2.1. Let $\{\varphi_n\}_{n \in \mathbb{N}}$ be a basis of $H$, and let $\{q_n\}_{n \in \mathbb{N}}$ be a sequence of scalars. For each $N \in \mathbb{N}$ and scalar sequence $\{f_n\}_{n=1}^N$, define

$$
Q \sum_{n=1}^N f_n \varphi_n = \sum_{n=1}^N q_n f_n \varphi_n.
$$

If the total variation of the sequence $\{q_n\}_{n \in \mathbb{N}}$ is finite, i.e., if

$$
\text{Var}(q) := \sum_{n=1}^\infty |q_{n+1} - q_n| < \infty,
$$

then $Q$ can be extended to a bounded linear operator on $H$, and

$$
\|Q\| \leq K \left( \text{Var}(q) + \limsup_{n \to \infty} |q_n| \right),
$$

where $K$ is a constant independent of the sequence $q$. 
In order to calculate the total variation, the following observation is useful. If \( f \) is a continuous function which is non-decreasing or non-increasing on the interval \((a, b)\), and if the sequence \( \{q_n\}_{n \in \mathbb{N}} \subset (a, b) \) is non-decreasing or non-increasing, then \( \text{Var}(f(q)) \leq |f(a) - f(b)| \).

Another ingredient in our counterexamples are Carleson measures. Let \( C_+ \) denote the open right half-plane, i.e., \( C_+ := \{ s \in \mathbb{C} \mid \Re(s) > 0 \} \). A positive measure \( \sigma \) in \( C_+ \) is a Carleson measure if there exists a constant \( m \) such that

\[
\sigma(\mathcal{Q}) \leq m \| s \|
\]

for all squares \( Q = \{ s = s_r + is_i \in C_+ \mid 0 < s_r < h, y_0 < s_i < y_0 + h \} \).

These measures play an important role in the theory of complex interpolation problems, see Garnett [4]. We use one of these results for the Hardy spaces \( H^p \).

The Hardy space \( H^p \), \( p \geq 1 \), is defined as the space of all functions which are holomorphic on \( C_+ \) and for which

\[
\sup_{r > 0} \int_{-\infty}^{\infty} |f(r + i\omega)|^p \, d\omega < \infty. \tag{15}
\]

\( H^p \) is a Banach space with its norm given by the \( p \)-th root of the expression in (15). The following result relates \( H^p \) with Carleson measures. For the proof we refer to Garnett [4, Theorem II.3.9].

**Lemma 2.2.** If \( \sigma \) is a Carleson measure, then

\[
\int |f|^p \, d\sigma \leq A\| f \|_{H^p}^p, \quad f \in H^p. \tag{16}
\]

More information on Carleson measures can be found in [4].

We are now in a position to present the example showing that weak admissibility of \( B \) for \( T(\cdot) \) does not imply admissibility.

**Example 2.3.** As in all our examples, we let \( H \) be a separable Hilbert space, and let \( \{ \varphi_n \}_{n \in \mathbb{N}} \) be a normalized basis for \( H \) which is not Hilbertian. Examples of such bases can be found in Singer [14, p. 428]. We let \( \{ \mu_n \}_{n \in \mathbb{N}} \subset (1, \infty) \) be a monotonically increasing sequence with \( \lim_{n \to \infty} \mu_n = \infty \) such that \( \sum_{n=1}^{\infty} \mu_n \delta_{\mu_n} \) is a Carleson measure. We may choose \( \mu_n := 2^n \), see [4, p. 288], but other choices are also possible.

First we construct a \( C_0 \)-semigroup on \( H \). For all \( t \geq 0 \) and \( x \in H \) of the form \( x = \sum_{n=1}^{\infty} f_n \varphi_n \), we define

\[
T(t) := \sum_{n=1}^{\infty} e^{-\mu_n t} f_n \varphi_n.
\]

Since the sequence \( \{ \mu_n \}_{n} \) is monotonically increasing and since \( \lim_{n \to \infty} \mu_n = \infty \), we get by Lemma 2.1 that \( T(t) \) has a linear bounded extension to \( H \). Thus \( T(t) \in \mathcal{L}(H) \), and

\[
\| T(t) \| \leq K e^{-t}, \quad t \geq 0. \tag{17}
\]

Clearly, \( T(0) = I \) and \( T(t)T(s) = T(t+s) \) for \( t, s \geq 0 \). We will show that \( T(\cdot) \) is strongly continuous. For each \( x \in H \), there exists a sequence \( \{ f_n \}_{n \in \mathbb{N}} \) of scalars such that (14) holds. Choose \( \varepsilon > 0 \) and choose \( N \) such that \( d = \max_{1 \leq n \leq N} | e^{-\mu_n t_0} - 1 | | f_n | \leq \varepsilon \). Then we have for \( t \in (0, t_0) \) that

\[
\| T(t)x - x \| \leq K e^{-t} + \sum_{n=1}^{N} | e^{-\mu_n t_0} - 1 | | f_n | + \varepsilon \leq [K + 2] \varepsilon.
\]

Thus \( T(\cdot) \) is a \( C_0 \)-semigroup on \( H \). This \( C_0 \)-semigroup was also used by Le Merdy [10] to show that there exists a uniformly bounded, compact \( C_0 \)-semigroup which is not equivalent to a contraction semigroup.

Let \( A \) denote the infinitesimal generator of \( T(\cdot) \). It is easy to see that

\[
A \varphi_n = -\mu_n \varphi_n, \quad n \in \mathbb{N}.
\]

We show that \( T(\cdot) \) is analytic. Since \( T(\cdot) \) is uniformly bounded, it is sufficient (see [12, Theorem 2.5.2]) to show that

\[
\|(sI - A)^{-1}\| \leq M, \quad s \in C_+ \tag{18}
\]

Let \( s = s_r + is_i \in C_+ \). Clearly, \( (sI - A)^{-1} \varphi_n = (1/\mu_n + \mu_n) \varphi_n \), for \( n \in \mathbb{N} \). In order to prove (18), we first estimate the variation of the sequence \( \gamma_n := 1/\mu_n + \mu_n \). For
each \( n \in \mathbb{N} \) we have

\[
|\gamma_{n+1} - \gamma_n| = \left| \frac{1}{s + \mu_{n+1}} - \frac{1}{s + \mu_n} \right| \\
= \int_{-\mu_{n+1}}^{-\mu_n} \frac{1}{(s-x)^2} \, dx \\
\leq \int_{-\mu_n}^{-\mu_{n+1}} \frac{1}{|s-x|^2} \, dx.
\]

Thus

\[
\text{Var}(\gamma) \leq \int_{-\infty}^{-1} \frac{1}{|s-x|^2} \, dx \\
= \int_{-\infty}^{-1} \frac{1}{|s|^2 + |x-s|^2} \, dx \\
\leq \int_{-\infty}^{0} \frac{1}{|s|^2 + |x-s|^2} \, dx = \frac{\pi}{2|s|}.
\]

Using Lemma 2.1 we get the following estimate for \( \| (sl-A)^{-1} \| \):

\[
\| (sl-A)^{-1} \| \leq K \left( \text{Var}(\gamma) + \lim_{n \to \infty} |\gamma_n| \right) \leq \frac{K\pi}{2|\text{Im } s|},
\]

where \( K > 0 \) is independent of \( s \). Thus \( T(\cdot) \) is analytic.

Next we construct an operator \( B \) which is weakly admissible but not admissible. We choose \( U = \ell^2(\mathbb{N}) \) and for each finite sequence \( \{v_n\}_{n=1}^N \), we define

\[
B\{v_n\}_{n=1}^N := \sum_{n=1}^N \sqrt{\mu_n} v_n \varphi_n.
\]

Since \( D(A^+) \) is the completion of \( H \) with respect to the norm

\[
\|x\|_{D(A^+)} = \|A^{-1}x\|_H,
\]

it is easy to see that \( B \) can be extended to an operator in \( \mathcal{L}(U, D(A^+)) \).

Next we prove that \( B \) is only weakly admissible.

(1) \( B \) is not an admissible control operator for \( T(\cdot) \).

Proof. Since \( T(\cdot) \) is exponentially stable, it is enough to show that \( B \) is not an infinite-time admissible control operator for \( T(\cdot) \).

Choose an arbitrary finite scalar sequence \( \{v_n\}_{n=1}^N \) and define

\[
u_N(t) := \sum_{n=1}^N \sqrt{\mu_n} v_n e^{-\mu_n t}, \quad t \geq 0,
\]

where \( \{e_n\}_{n \in \mathbb{N}} \) is the standard basis of \( \ell^2(\mathbb{N}) \), i.e., \( (e_n)_k = 1 \) if \( k = n \) and \( (e_n)_k = 0 \) otherwise. Clearly,

\[
\|u_N\|^2_{L^2(0, \infty; \ell^2(\mathbb{N}))} = \sum_{n=1}^N \mu_n |v_n|^2 \int_0^\infty e^{-2\mu_n t} \, dt \\
= \frac{1}{2} \sum_{n=1}^N |v_n|^2.
\]

Furthermore, using the fact that \( B e_n = \sqrt{\mu_n} \varphi_n \) and \( T(t) \varphi_n = e^{-\mu_n t} \varphi_n \), we see that

\[
\int_0^\infty T(t) Bu_N(t) \, dt = \int_0^\infty \sum_{n=1}^N \mu_n v_n e^{-\mu_n t} \varphi_n \, dt \\
= \frac{1}{2} \sum_{n=1}^N v_n \varphi_n.
\]

If \( B \) was infinite-time admissible, then there would exist a constant \( M > 0 \) such that

\[
\left\| \int_0^\infty T(t) Bu(t) \, dt \right\|_H \leq M \|u\|_{L^2(0, \infty; \ell^2(\mathbb{N}))},
\]

\[u \in \ell^2(0, \infty; \ell^2(\mathbb{N})).\]

(2) \( B \) is a weakly admissible control operator for \( T(\cdot) \) i.e., for every \( v \in \ell^2(\mathbb{N}) \), \( Bv \) is an infinite-time admissible control operator for \( T(\cdot) \).
Proof. Let \( v = \{v_n\}_{n \in \mathbb{N}} \in L^2(\mathbb{N}) \), and let \( v_N := \{v_n\}_{n=1}^N \). For \( u \in L^2(0, \infty) \) we get
\[
\left\| \int_0^\infty T(\tau)Bv_N u(\tau) \, d\tau \right\|_H
\]
\[
= \left\| \int_0^\infty \sum_{n=1}^N e^{-\mu_n \tau} v_n \sqrt{\mu_n} \varphi_n u(\tau) \, d\tau \right\|_H
\]
\[
= \left\| \sum_{n=1}^N v_n \sqrt{\mu_n} \int_0^\infty e^{-\mu_n \tau} u(\tau) \, d\tau \varphi_n \right\|_H
\]
\[
\leq \left\| \sum_{n=1}^N \left| v_n \sqrt{\mu_n} \hat{\mu}(\mu_n) \right| \right\|_H
\]
\[
\leq \left( \sum_{n=1}^N |v_n|^2 \right)^{1/2} \left( \sum_{n=1}^N \left| \sqrt{\mu_n} \hat{\mu}(\mu_n) \right|^2 \right)^{1/2}
\]
\[
\leq M_2 \|v\| \|\hat{u}\|_{H^2}, \tag{22}
\]
where we have used Lemma 2.2 and the fact that the Laplace transform of any \( L^2(0, \infty) \) function lies in \( H^2 \). Since \( \|\hat{u}\|_{H^2} = 2\pi \|u\|_{L^2(0, \infty)} \), we have shown that \( Bu_N \) is an admissible control operator for \( T(\cdot) \).

For \( N \to \infty \), we have that \( Bu_N \to Bu \) in \( D(A^*') \), and hence
\[
\int_0^\infty T(\tau)Bu_N u(\tau) \, d\tau \to \int_0^\infty T(\tau)Bu u(\tau) \, d\tau
\]
in \( D(A^*') \). \( \Box \)

On the other hand, (22) shows that the sequence \( \int_0^\infty T(\tau)Bu_N u(\tau) \, d\tau \) is bounded in \( H \), which implies convergences (23) also holds in the weak topology of \( H \). By the weak compactness of the unit ball in \( H \), \( \int_0^\infty T(\tau)Bu u(\tau) \, d\tau \in H \) and
\[
\left\| \int_0^\infty T(\tau)Bu u(\tau) \, d\tau \right\|_H \leq M_3 \|u\|_{L^2(0, \infty)}. \tag{24}
\]

Thus, \( Bu \) is an admissible control operator for \( T(\cdot) \).

If \( B \) is weakly admissible, then it is not hard to show that \( Bu \) satisfies the sequence of estimates (12), with \( M = M_r \), see [15, Section 4.2]. Using the uniform boundedness theorem, we conclude that every weakly admissible \( B \) satisfies (12). Hence the previous example shows that this condition is not sufficient for admissibility. Yet we will show that the input operator from Example 2.3 satisfies a sequence of estimates, which is stronger than (12), and thus showing that this stronger sequence of estimates is not sufficient either. Here we explicitly use the fact that \( \mu_n = 2^n \).

Let \( s \) be an element of \( \mathbb{C}_+ \), and let \( v = \{v_k\}_{k=1}^\infty \in L^2(\mathbb{N}) \) have norm one. We have the following estimate:
\[
\| (sI - A)^{-n} Bu \|^2 \leq \left( \sum_{k=1}^\infty \frac{\sqrt{2^n}}{(s + 2^k)^n} |v_k| \right)^2
\]
\[
\leq \left( \sum_{k=1}^\infty \frac{\sqrt{2^n}}{(\text{Re}(s) + 2^k)^n} |v_k| \right)^2
\]
\[
\leq \sum_{k=1}^\infty \frac{2^k}{(\text{Re}(s) + 2^k)^{2n}},
\]
where we have used the Cauchy–Schwarz inequality. In order to estimate this last expression, we introduce the monotonically decreasing sequence \( a_k := 1/(\text{Re}(s) + k)^{2n} \). Then for \( N \geq 2^k \) we have
\[
\sum_{k=1}^N a_k \geq a_1 + a_2 + (a_3 + a_4) + \cdots + (a_{2^{k-1}} + \cdots + a_{2^k})
\]
\[
\geq a_2 + 2a_4 + \cdots + 2^{K-1}a_{2^K} = \frac{1}{2} \sum_{k=1}^K 2^k a_{2^k},
\]
and so
\[
\sum_{k=1}^\infty \frac{2^k}{(\text{Re}(s) + 2^k)^{2n}} \leq 2 \sum_{k=1}^\infty \frac{1}{(\text{Re}(s) + k)^{2n}}.
\]

Using this in our estimate of \( \| (sI - A)^{-n} Bu \| \), we obtain that
\[
\| (sI - A)^{-n} Bu \|^2 \leq 2 \sum_{k=1}^\infty \frac{1}{(\text{Re}(s) + k)^{2n}}
\]
\[
\leq 2 \int_0^\infty \frac{1}{(\text{Re}(s) + t)^{2n}} \, dt
\]
\[
\leq \frac{2}{2n-1} \left( \frac{1}{(\text{Re}(s))^{2n-1}} \right).
\]
3. Admissibility and weak infinite-time admissibility does not imply infinite-time admissibility

In the previous section we have shown that weak admissibility does not imply admissibility. From (24) we see that the input operator in our example is weakly infinite-time admissible. Hence, we already proved that weak infinite-time admissibility does not imply admissibility, and thus not infinite-time admissibility either. However, if $B$ is admissible, would weak infinite-time admissibility imply infinite-time admissibility? In the next example we show that this does not hold either. Note that in this example the operators $A$ and $B$ are compact elements of $\mathcal{L}(H)$ and $\mathcal{L}(\ell^2(\mathbb{N}),H)$, respectively, and that $T(\cdot)$ is bounded and strongly stable. In particular, $B$ is an admissible control operator for $A$. Furthermore, note that the operator $A$ in this example is the inverse of the operator $A$ in the previous example.

Example 3.1. Let $\{\lambda_n\}_{n \in \mathbb{N}} \subset (0,1)$ be a monotonically decreasing sequence with $\lim_{n \to \infty} \lambda_n = 0$, and such that $\sum_{n=1}^{\infty} \lambda_n \delta_{n} \in \text{Car} \cdot \mathbb{C}_+$. We could for example choose $\lambda_n := 2^{-n}$, see Garnett [4, p. 288]. We take $\{\varphi_n\}_{n \in \mathbb{N}}$ to be the same as in Example 2.3.

We now define $A$ by

$$A\varphi_n = -\lambda_n \varphi_n, \quad n \in \mathbb{N}.$$ 

Since the sequence $\{\lambda_n\}_{n}$ is monotonically decreasing it is easy to see that $\{\lambda_n\}_{n \in \mathbb{N}}$ is of bounded variation. Now by Lemma 2.1, we get that $A$ has a bounded linear extension to $H$, that is $A \in \mathcal{L}(H)$. Let $T(\cdot)$ be the $C_0$-semigroup generated by $A$, that is

$$T(t)\varphi_n = e^{-\lambda_n t} \varphi_n, \quad t \geq 0, \quad n \in \mathbb{N}.$$ 

The operators $A$ and $T(\cdot)$ have some nice properties.

1. $T(\cdot)$ is bounded and strongly stable.

Proof. By Lemma 2.1 we have for $t \geq 0$

$$\|T(t)\| \leq 2K,$$

and thus the $C_0$-semigroup $T(\cdot)$ is bounded.

Next we show that $T(\cdot)$ is strongly stable. Let $x = \sum_{n=1}^{\infty} f_n \varphi_n \in H$ and $\varepsilon > 0$. Then there exists an $N \in \mathbb{N}$ such that $x_N := \sum_{n=1}^{N} f_n \varphi_n$ satisfies

$$\|x - x_N\|_H < \varepsilon.$$ 

Thus, for sufficiently large $t > 0$ we have

$$\|T(t)x\| \leq \|T(t)x - T(t)x_N\| + \|T(t)x_N\| \leq \|T(t)\| \|x - x_N\| + \sum_{n=1}^{N} e^{-\lambda_n t} f_n \varphi_n \| \leq 2Ke + \sum_{n=1}^{N} e^{-\lambda_n t} f_n \varphi_n \| \leq 2Ke + \varepsilon,$$

and so $T(\cdot)$ is strongly stable.

(2) The operator $A$ is compact.

Proof. Define $A_N, \ N \in \mathbb{N}$, by

$$A_N \varphi_n = \begin{cases} -\lambda_n \varphi_n, & n \leq N, \\ 0, & n > N. \end{cases}$$

Clearly, $A_N$ has rank $N$. Using Lemma 2.1, we get the estimate

$$\|A - A_N\| \leq 2K\lambda_{N+1} \to 0 \quad \text{as} \quad N \to \infty,$$ 

which shows that $A$ is compact.

Next we define the control operator $B$. We again choose $U = \ell^2(\mathbb{N})$, and for every finite sequence $\{v_n\}_{n=1}^{N}$ we define

$$B\{v_n\}_{n=1}^{N} = \sum_{n=1}^{N} \sqrt{\lambda_n} v_n \varphi_n.$$ 

(3) $B$ can be extended to a bounded linear operator.

Proof. We have

$$\|B\{v_n\}_{n=1}^{N}\| = \left\| \sum_{n=1}^{N} \sqrt{\lambda_n} v_n \varphi_n \right\| \leq \sum_{n=1}^{N} \sqrt{\lambda_n} |v_n| \|\varphi_n\|$$

$$\leq \sum_{n=1}^{N} \sqrt{\lambda_n} |v_n| \leq \sqrt{\left( \sum_{n=1}^{N} \lambda_n \right) \sum_{n=1}^{N} |v_n|^2}.$$ 

Thus we have that

$$\|B\{v_n\}_{n=1}^{N}\|^2 \leq \left( \sum_{n=1}^{N} \lambda_n \right) \sum_{n=1}^{N} |v_n|^2 \leq C \|\{v_n\}_{n=1}^{N}\|_{\ell^2(\mathbb{N})},$$
where \( C := \sum_{n=1}^{\infty} \lambda_n < \infty \), since \( \sum_{n=1}^{\infty} \lambda_n \delta_{\lambda_n} \) is a Carleson measure with support in \((0, 1)\). This shows that \( B \) has a bounded linear extension, i.e., \( B \in \mathcal{L}(\ell^2(\mathbb{N}), H) \). In particular, \( B \) is an admissible control operator for \( T(\cdot). \)

(4) The operator \( B \) is compact. This is shown similar as in Part (2), using estimates similar to those in Part (3) instead of Lemma 2.1.

(5) \( B \) is not an infinite-time admissible control operator for \( T(\cdot). \) This is shown in the same way as in Example 2.3.

(6) Similarly, as in Example 2.3, we can show that for every \( v \in U, Bv \) is an infinite-time admissible control operator for \( T(\cdot). \) Furthermore, as in (22) and (24) we have that

\[
\left\| \int_0^\infty T(\tau)Bvu(\tau) \, d\tau \right\| \leq M_2 \|v\| \|u\| L^2(0, \infty). \tag{26}
\]

(7) There exists a constant \( K > 0 \) such that

\[
\| (sI - A)^{-1} Bv \| \leq \frac{K}{\sqrt{\text{Re}(s)}}, \quad s \in \mathbb{C}, \ \text{Re} (s) > 0.
\]

Proof. Substituting \( u(\tau) = e^{-\tau} \) in (26), where \( \text{Re}(s) > 0 \) gives that

\[
\| (sI - A)^{-1} Bv \| \leq \frac{M_2 \|v\|}{\sqrt{\text{Re}(s)}}.
\]

Since this holds for all \( v \in H \) we have proved the assertion.

4. A semigroup example

A direct consequence of the Hille–Yosida theorem is that a \( C_0 \)-semigroup \( T_c(\cdot) \) is uniformly bounded if and only if there exists a constant \( M \) such that its generator \( A_c \) satisfies

\[
\| (sI - A_c)^{-1} \| \leq \frac{M}{\text{Re}(s)}, \quad \text{for all } n \in \mathbb{N} \text{ and } s \in \mathbb{C}_+.
\]

If \( T_c(\cdot) \) is a \( C_0 \)-semigroup on the Hilbert space \( H_c \), then its growth bound is negative if and only if \( (sI - A_c)^{-1} \) is uniformly bounded in the open right half-plane. Motivated by this result, one wonders if the first inequality of the Hille–Yosida theorem is sufficient to determine the exact growth of the semigroup. More precisely, suppose that the infinitesimal generator \( A_c \) satisfies

\[
\| (sI - A_c)^{-1} \| \leq \frac{M}{\text{Re}(s)} \quad \text{for all } s \in \mathbb{C}_+; \tag{27}
\]

does this imply that \( T_c(\cdot) \) is uniformly bounded?

Using the example of the previous section we show that this is in general not true, by constructing a \( C_0 \)-semigroup for which the infinitesimal generator \( A_c \) satisfies (27) but

\[
\lim_{t \to \infty} \| T_c(t) \| = \infty. \tag{28}
\]

We remark that estimate (27) implies that \( \| T(t) \| \leq M(1 + t) \), but we do not know how sharp this estimate is.

Furthermore, we would like to remark that if there exists a \( \gamma \in [0, 1) \) such that the infinitesimal generator \( A_c \) satisfies

\[
\| (sI - A_c)^{-1} \| \leq \frac{M}{\text{Re}(s)^\gamma} \quad \text{for all } s \in \mathbb{C}_+,
\]

then the \( C_0 \)-semigroup is exponentially stable, see [15, Lemma 3.11.7].

Consider the operators \( A \) and \( B \) of Example 3.1, and let \( T(\cdot) \) denote the bounded semigroup generated by \( A \). With these operators we define the semigroup \( T_c(\cdot) \) on \( H \oplus L^2(0, \infty; \ell^2(\mathbb{N})) \) as

\[
T_c(t) \begin{pmatrix} x \\ f \end{pmatrix} = \begin{pmatrix} T(t)x + \int_0^t T(t - \tau)Bf(\tau) \, d\tau \\ f(t + \cdot) \end{pmatrix},
\]

\( t \geq 0 \).

\( B \) is a bounded operator, and hence \( B \) is an admissible control operator for \( T(\cdot). \) According to Engel [3], this implies that \( T_c(\cdot) \) is a \( C_0 \)-semigroup on \( H \oplus L^2(0, \infty; \ell^2(\mathbb{N})) \). Since \( B \) is not infinite-time admissible we know that \( T_c(\cdot) \) cannot be a bounded semigroup. However, we will show that its infinitesimal generator satisfies (27).

By taking the Laplace transform of the semigroup, we see that the resolvent is given by

\[
(sI - A_c)^{-1} \begin{pmatrix} x \\ f \end{pmatrix} = \begin{pmatrix} (sI - A)^{-1}x + (sI - A)^{-1}Bf(s) \\ f(t + \cdot)(s) \end{pmatrix}.
\]

Since the left shift is a contraction semigroup we know that \( L^2(0, \infty; \ell^2(\mathbb{N})) \)-norm of \( f(t + \cdot)(s) \) is
bounded by $\|f\| \times 1/\text{Re}(s)$. Furthermore, since $T(\cdot)$ is a bounded semigroup, a similar estimate holds for $(sI - A)^{-1}$. Thus, we have that for $s \in \mathbb{C}_+$

$$
\| (sI - A_e)^{-1} \begin{pmatrix} x \\ f \end{pmatrix} \|_2^2 
\leq \frac{2M^2}{\text{Re}(s)^2} \|x\|^2 + 2\|(sI - A)^{-1}B\|^2 \|\hat{f}(s)\|^2
+ \frac{1}{\text{Re}(s)^2} \|f\|^2.
$$

(29)

Since $f \in L^2(0, \infty; l^2(\mathbb{N}))$ we have that

$$
\|\hat{f}(s)\| \leq \|f\|/\sqrt{2\text{Re}(s)} \quad \text{for all } s \in \mathbb{C}_+.
$$

(30)

In Example 3.1 we proved the existence of a constant $K > 0$ such that

$$
\| (sI - A)^{-1}B \| \leq K/\sqrt{\text{Re}(s)} \quad \text{for all } s \in \mathbb{C}_+.
$$

(31)

Combining (29)–(31) gives that $A_e$ satisfies estimate (27). Since the corresponding semigroup is unbounded, we have shown that estimate (27) is not sufficient to conclude the boundedness of a $C_0$-semigroup.

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References