

# The signomial global optimization algorithm

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November 3, Åbo, Finland



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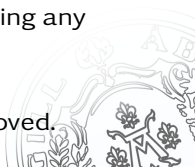
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- ▶ As the PLFs are updated, the approximations are improved.





## The considered class of MINLP problems

### The MISP problem formulation

$$\begin{array}{lll} \text{minimize} & f(\mathbf{x}) & \mathbf{x} = (x_1, x_2, \dots, x_I) \\ \text{subject to} & \mathbf{Ax} = \mathbf{a} \quad \mathbf{Bx} \leq \mathbf{b} & \\ & g_n(\mathbf{x}) \leq 0 & n = 1, 2, \dots, J_n \\ & q_m(\mathbf{x}) + \sigma_m(\mathbf{x}) \leq 0 & m = 1, 2, \dots, J_m \end{array}$$



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- ▶ The vector  $\mathbf{x}$  can contain both continuous and integer-valued variables.
- ▶ The differentiable real functions  $f$  and  $g$  are (pseudo)convex, and the functions  $q$  and  $\sigma$  are convex and signomial respectively.



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$$\sigma(\mathbf{x}) = \sum_{j=1}^J c_j \prod_{i=1}^I x_i^{p_{ji}}, \quad c_j, p_{ji} \in \mathbb{R}.$$

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### Example

$$q(x_1, x_2) + \sigma(x_1, x_2) = \underbrace{x_1^2 + e^{x_2}}_{q(x_1, x_2)} + \underbrace{2.3x_1^{0.35} - 4x_1x_2^{0.5} + x_1x_2}_{\sigma(x_1, x_2)}.$$

# The transformation approach



## Convexification and relaxation of MISP problems

### 1. Convexification

- ▶ Every signomial term can be transformed to convex form by using single-variable transformations.
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- ▶ Additional variables and a number of nonlinear equality constraints defining the inverse transformations are obtained.

### 2. Underestimation, convexification and relaxation

- ▶ By using properly selected transformations, the convexified terms are underestimated when the inverse transformations are approximated by piecewise linear functions.
- ▶ The MINLP problem is now convexified and relaxed.



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### Positive term

One of the following is true:

- ▶ All powers are negative

Example:  $x_1^{-0.5} x_2^{-2}$

- ▶ One power is positive, the rest negative, and the sum of the powers is  $\geq 1$

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### Negative term

- ▶ All powers are positive and the sum of the powers is  $\leq 1$

Example:  $-x_1^{0.5} x_2^{0.5}$



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For all  $i, j : p_{ji} > 0$ :

- ▶ Exponential transformation (ET)

$$x_i = e^{X_{ji}}$$

- ▶ Positive power transformation (PPT)

$$x_i = X_{ji}^{Q_{ji}}$$

$$\begin{cases} Q_{ji} \geq 1 & \text{if } i = k, \\ Q_{ji} < 0 & \text{if } i \neq k, \end{cases} \quad \sum_{i=1}^l p_{ji} Q_{ji} \geq 1.$$

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- ▶ Power transformation (PT)

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$$\begin{cases} 0 < Q_{ji} \leq 1 & \text{if } p_{ji} > 0, \\ Q_{ji} < 0 & \text{if } p_{ji} < 0, \end{cases}$$

$$\sum_{i=1}^l p_{ji} Q_{ji} \leq 1.$$

- ▶ The convexified term is underestimated by replacing the inverse transformations ( $X_{ji} = \ln x_i$  or  $X_{ji} = x_i^{1/Q_{ji}}$ ) with PLFs.



## Examples of the transformations

### Transforming a positive signomial term

Original term	Transformation	Transformed term
$x_1^{1.2} x_2^{0.1} x_3^{-1} x_4^{-2}$	PPT	$x_1^{4.1} x_2^{-0.1} x_3^{-1} x_4^{-2}$
	NPT	$x_1^{-1.2} x_2^{-0.1} x_3^{-1} x_4^{-2}$
	ET	$e^{1.2x_1} e^{0.1x_2} x_3^{-1} x_4^{-2}$





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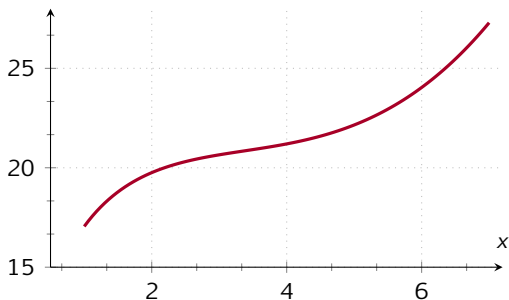
### Transforming a negative signomial term

Original term	Transformation	Transformed term
$-x_1^{-1} x_2^{0.5}$	PT	$-x_1^{0.5} x_2^{0.5}$



**Example: a univariate nonconvex signomial term**

$$f(x) = \underbrace{-8x + 0.05x^3}_{\text{convex}} + \underbrace{25x^{0.5}}_{\text{nonconvex}}, \quad 1 \leq x \leq 7$$



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- A convex underestimator is obtained by applying the ET

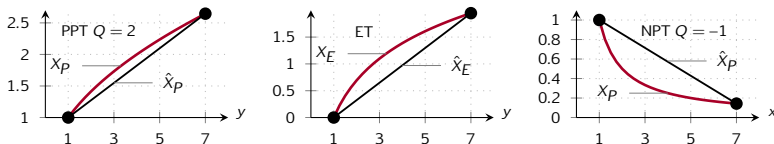
$$\hat{f}_1(x, \hat{X}_E) = -8x + 0.05x^3 + 25e^{0.5\hat{X}_E}$$

or one of the PPT or NPT

$$\hat{f}_2(x, \hat{X}_P) = -8x + 0.05x^3 + 25\hat{X}_P^{0.5Q}, \quad \overbrace{Q \geq 2}^{\text{PPT}} \text{ or } \overbrace{Q < 0}^{\text{NPT}}.$$

Here,  $\hat{X}_E$  and  $\hat{X}_P$  are piecewise linear approximations of the inverse transformations  $X_E = \ln x$  and  $X_P = x^{1/Q}$ .

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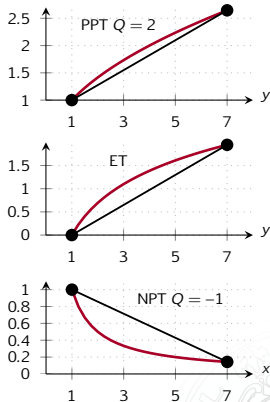
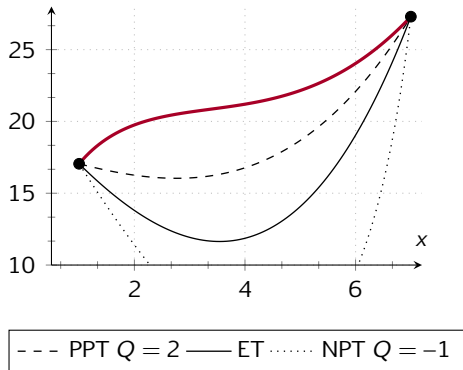
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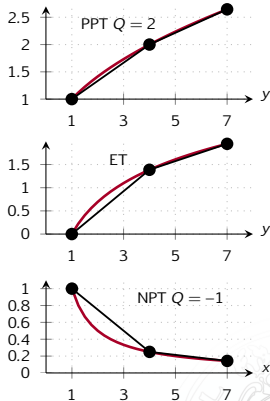
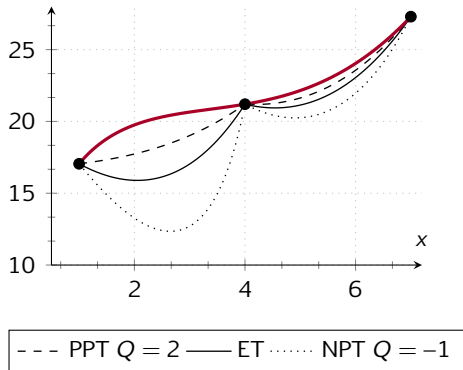
## Example: a univariate nonconvex signomial term

- The underestimators are improved by adding additional breakpoints to the PLFs



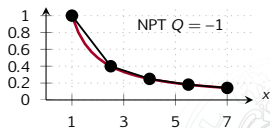
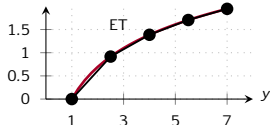
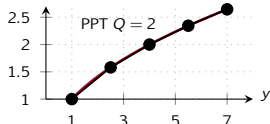
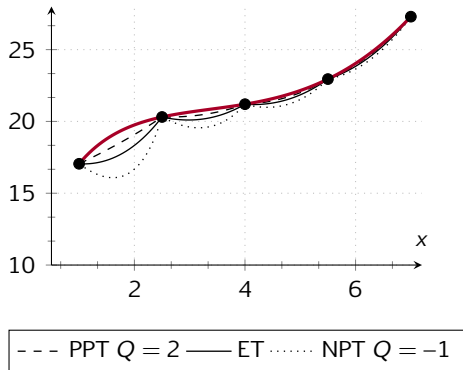
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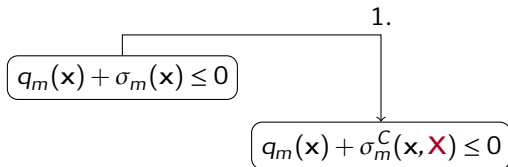


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## Transformation of the signomial constraints

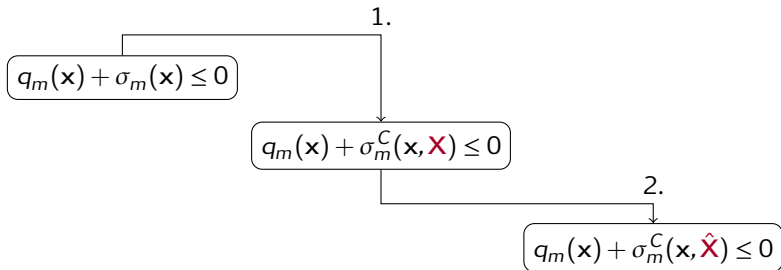


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Nonconvexities moved to  $X_{ji} = T_{ji}^{-1}(x_i)$ .

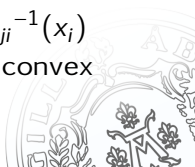




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2. **Underestimation** of  $\sigma_m^C$  by approximating  $X_{ji} = T_{ji}^{-1}(x_i)$  with PLFs  $\hat{X}_{ji}$ . The integer-relaxed problem is now convex and overestimates the original problem.



# The signomial global optimization algorithm

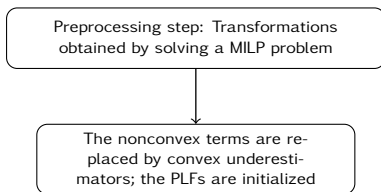


## Flowchart of the SGO-algorithm

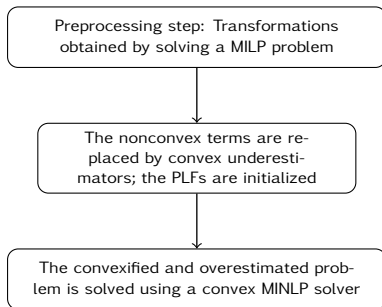
Preprocessing step: Transformations  
obtained by solving a MILP problem



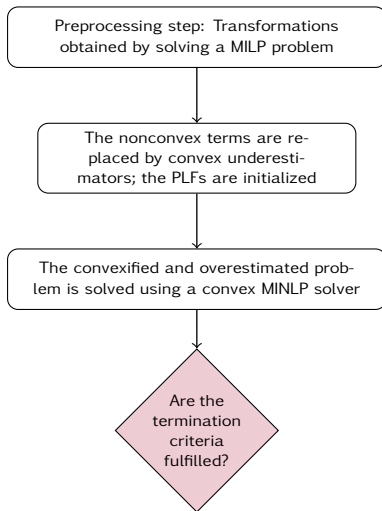
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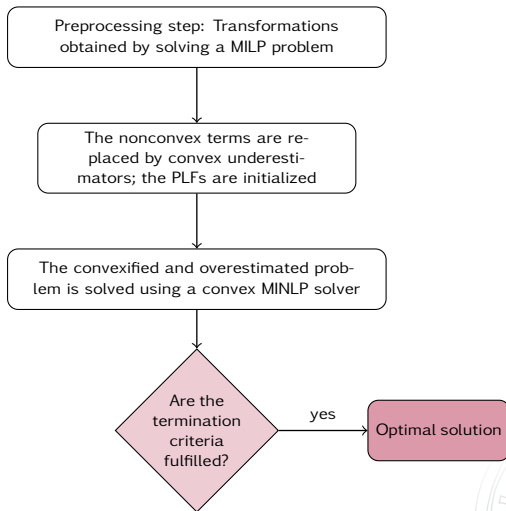
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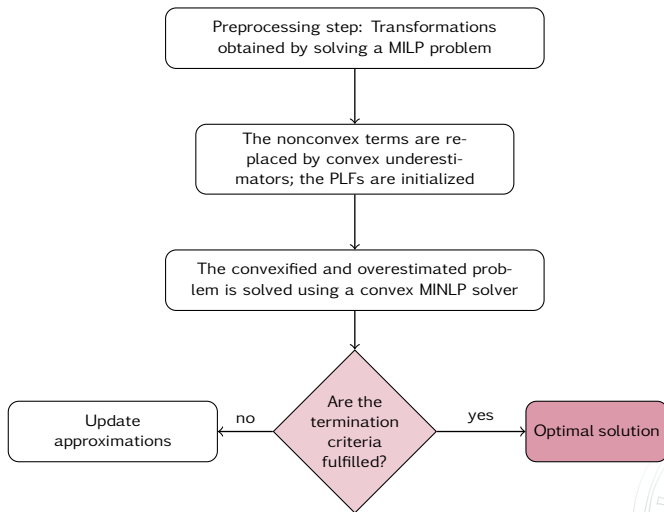
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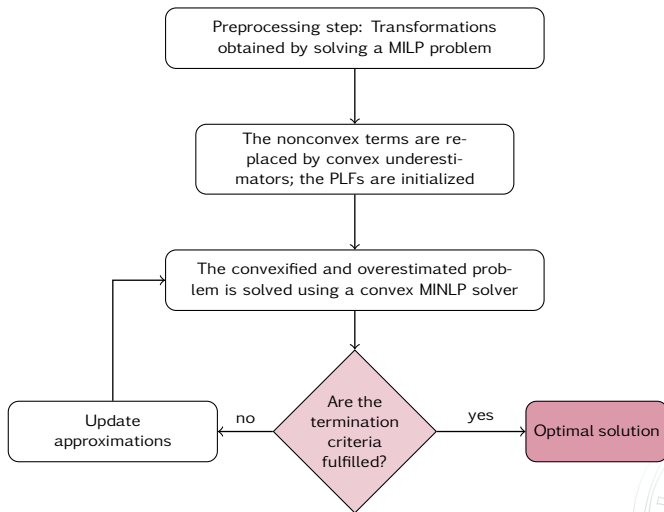


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The transformations  $x_i = T_{ji}(X_{ji})$  are applied termwise to all  $J_T$  nonconvex signomial terms (in the problem).

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### Solution approach

Create a MILP problem formulation, whose solution determines the optimal set of transformations required to transform the signomial terms, specified by the coefficients  $c_j$  and powers  $p_{ji}$ .

## The objective function of the MILP problem

For a MISP problem with  $J_T$  signomial terms and  $I$  variables:

$$\begin{aligned} \text{minimize} \quad & \delta_R \sum_{i: x_i \in R} B_i + \delta_Z \sum_{i: x_i \in Z} B_i + \delta_I \sum_{i=1}^I \sum_{j_1=1}^{J_T} \sum_{\substack{j_2=1 \\ j_2 \neq j_1}}^{J_T} \gamma_{j_1 j_2 i} \\ & + \sum_{i=1}^I \sum_{j=1}^{J_T} (\delta_{NT} b_{ji} + \delta_{NS} \Delta_{ji} + \delta_{ET} b_{ji}^{ET} + \delta_{PT} b_{ji}^{PT} + \delta_P \beta_{ji}) \end{aligned}$$



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### Parameters and variables

- ▶ Strategy parameters:  $\delta_R, \delta_Z, \delta_I, \delta_{NT}, \delta_{NS}, \delta_{ET}, \delta_{PT}, \delta_P$
- ▶ Decision variables (binaries):
  - ▶  $x_i$  is transformed in any term  $\Rightarrow B_i = 1$
  - ▶  $x_i$  is transformed in the  $j$ -th term  $\Rightarrow b_{ji} = 1$
  - ▶ ET or PT used on  $x_i$  in the  $j$ -th term  $\Rightarrow b_{ji}^{ET} = 1 \vee b_{ji}^{PT} = 1$
  - ▶  $p_{ji} Q_{ji} > 0 \Rightarrow \beta_{ji} = 1$
  - ▶ different transformations for  $x_i$  in terms  $j_1$  and  $j_2 \Rightarrow \gamma_{j_1 j_2 i} = 1$
- ▶ Penalties (real-valued)  $\Delta_{ji}$  for large/small values of  $Q_{ji}$

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- ▶ The values of the parameters in the objective function determine in what respect the set of transformations will be optimal
- ▶ The following aspects can be taken into account
  - ▶ penalize number of original variables transformed





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  - ▶ penalize number of original variables transformed
  - ▶ penalize number of nonidentical transformations for the same variables
  - ▶ penalize total number of transformations
  - ▶ penalize numerically unstable transformations (e.g.  $Q = -0.001$ )



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$$\text{minimize} \quad \dots + \sum_{i=1}^I \sum_{j=1}^{J_T} (\delta_{NT} b_{ji} + \delta_{NS} \Delta_{ji} + \delta_{ET} b_{ji}^{ET} + \delta_{PT} b_{ji}^{PT} + \delta_P \beta_{ji})$$

- ▶ The values of the parameters in the objective function determine in what respect the set of transformations will be optimal
- ▶ The following aspects can be taken into account
  - ▶ penalize number of original variables transformed
  - ▶ penalize number of nonidentical transformations for the same variables
  - ▶ penalize total number of transformations
  - ▶ penalize numerically unstable transformations (e.g.  $Q = -0.001$ )
  - ▶ favor the ET or the PTs for positive terms



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## An illustrative example



## Two-dimensional example

- The SGO algorithm is now applied to the following MISP problem

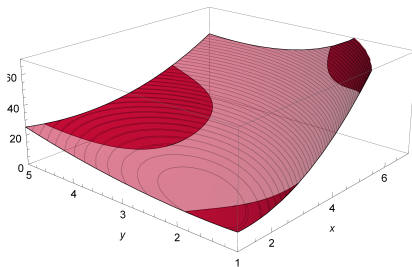
$$\begin{array}{ll}\text{minimize} & (x-4)^2 + (y-1)^2 + 2.5x^2y^{-1} \\ \text{subject to} & -20 + 8x - 1.5y^{0.5} + 11y + 0.9y^2 \\ & \quad + 0.1x^2y^2 - x^2 + 0.2x^{1.5}y^{0.5} - 1.2xy - 2x^{0.5}y^2 \leq 0 \\ & 1 \leq x \leq 7, \quad 1 \leq y \leq 5, \quad x \in \mathbb{Z}^+, \quad y \in \mathbb{R}^+\end{array}$$



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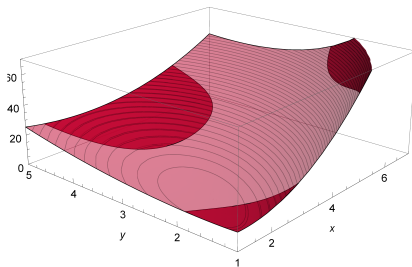
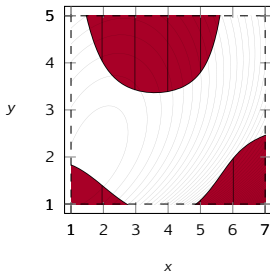




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## Transformation of the problem

- Optimizing the transformations gives that three transformations are needed

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$$\dots + 0.1x^2 \overbrace{y^2}^{y = Y_1^{-0.5}} - \overbrace{x^2}^{y = Y_1^{-0.5}} + 0.2x^{1.5} \overbrace{y^{0.5}}^{y = Y_1^{-0.5}} - 1.2 \overbrace{xy}^{y = Y_2^{0.25}} - 2x^{0.5} \overbrace{y^2}^{y = Y_2^{0.25}} \leq 0.$$



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$$\begin{array}{c} \overbrace{y = Y_1^{-0.5}} \\ \overbrace{y = Y_2^{0.25}} \\ \dots + 0.1x^2 \textcolor{red}{y}^2 - \textcolor{red}{x}^2 + 0.2x^{1.5} \textcolor{red}{y}^{0.5} - 1.2 \textcolor{red}{x} \textcolor{red}{y} - 2x^{0.5} \textcolor{red}{y}^2 \leq 0. \\ \underbrace{\hspace{10em}} \\ x = X_1^{0.5} \end{array}$$



## Transformation of the problem

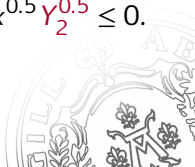
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$$\underbrace{\dots + 0.1x^2 y^2 - x^2 + 0.2x^{1.5} y^{0.5}}_{x = X_1^{0.5}} - 1.2xy - 2x^{0.5} y^2 \leq 0.$$

- This gives the following convexified constraint

$$\dots + 0.1x^2 Y_1^{-1} - X_1 + 0.2x^{1.5} Y_1^{-0.25} - 1.2X_1^{0.5} Y_2^{0.25} - 2x^{0.5} Y_2^{0.5} \leq 0.$$



## Linear approximation of the transformations

- When the equality constraints

$$X_1 = x^2, \quad Y_1 = y^{-2}, \quad \text{and} \quad Y_2 = y^4$$

are replaced with the PLFs  $\hat{X}_1$ ,  $\hat{Y}_1$  and  $\hat{Y}_2$ , the terms are also underestimated.

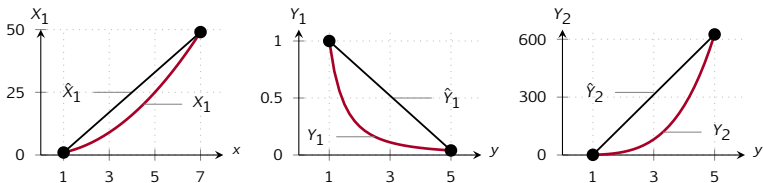


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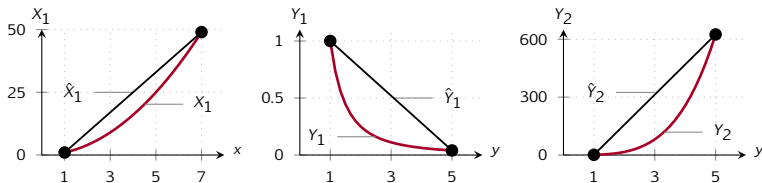


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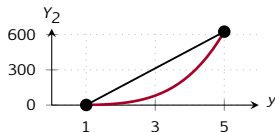
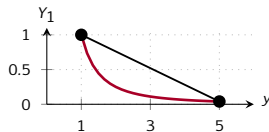
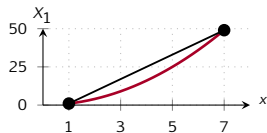
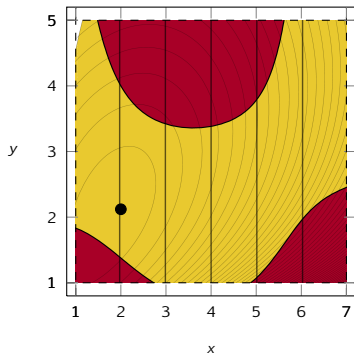
are replaced with the PLFs  $\hat{X}_1$ ,  $\hat{Y}_1$  and  $\hat{Y}_2$ , the terms are also underestimated.



- As new breakpoints are added to the PLFs, the approximations will improve.



## Iteration 1



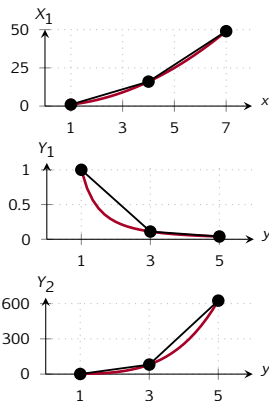
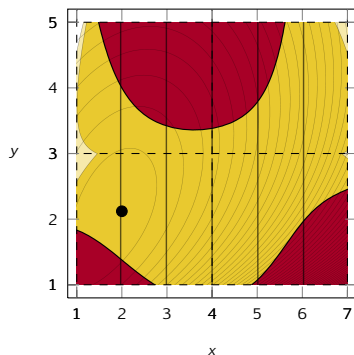
- ▶ The value of the objective function is 9.97 for  $x = 2$  and  $y = 2.12$ .
- ▶ The original signomial constraint is not fulfilled:

$$\underbrace{\dots + 0.1x^2y^2 - x^2 + 0.2x^{1.5}y^{0.5} - 1.2xy - 2x^{0.5}y^2}_{= 1.996, \text{ when } x=2, y=2.12} \leq 0$$

- ▶ Not the global solution to the nonconvex problem!



## Iteration 2



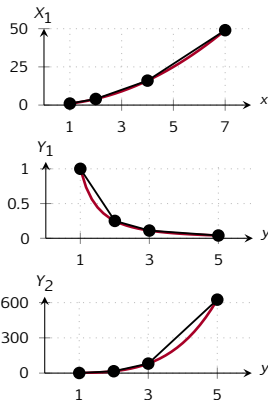
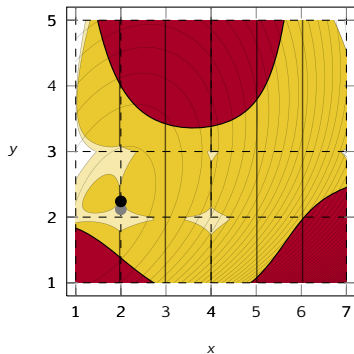
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$$\underbrace{\dots + 0.1x^2y^2 - x^2 + 0.2x^{1.5}y^{0.5} - 1.2xy - 2x^{0.5}y^2}_{= 1.995, \text{ when } x=2, y=2.12} \leq 0$$

- ▶ Not the global solution to the nonconvex problem!



## Iteration 3



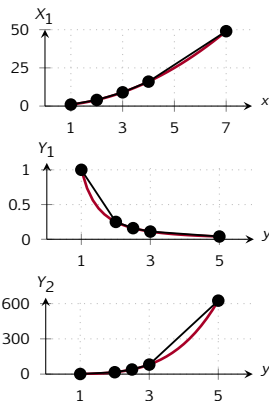
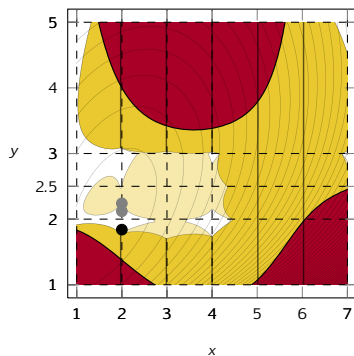
- ▶ The value of the objective function is 10.00 for  $x = 2$  and  $y = 2.24$ .
- ▶ The original signomial constraint is not fulfilled:

$$\underbrace{\dots + 0.1x^2y^2 - x^2 + 0.2x^{1.5}y^{0.5} - 1.2xy - 2x^{0.5}y^2}_{= 2.195, \text{ when } x=2, y=2.24} \leq 0$$

- ▶ Not the global solution to the nonconvex problem!



## Iteration 4



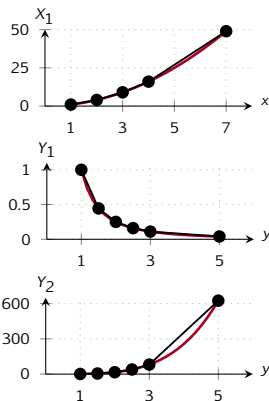
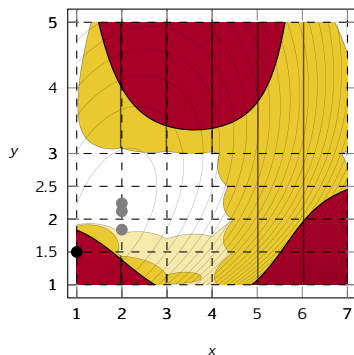
- ▶ The value of the objective function is 10.14 for  $x = 2$  and  $y = 1.84$ .
- ▶ The original signomial constraint is not fulfilled:

$$\underbrace{\dots + 0.1x^2y^2 - x^2 + 0.2x^{1.5}y^{0.5} - 1.2xy - 2x^{0.5}y^2}_{= 1.377, \text{ when } x=2, y=1.84} \leq 0$$

- ▶ Not the global solution to the nonconvex problem!



## Iteration 5



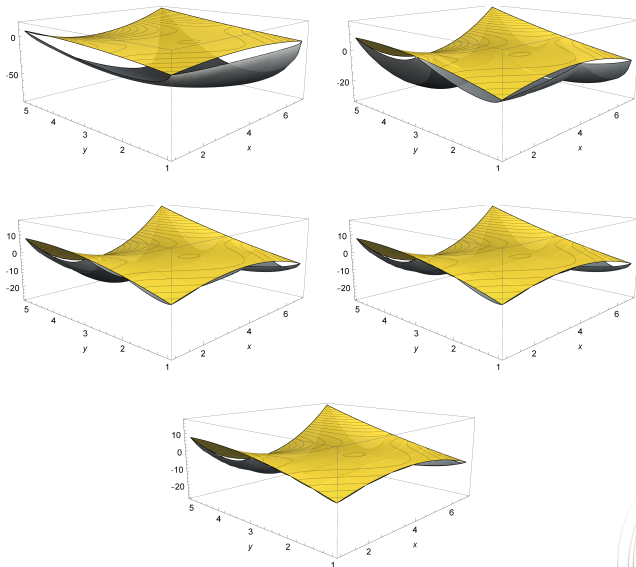
- ▶ The value of the objective function is 10.92 for  $x = 1$  and  $y = 1.5$ .
- ▶ The original signomial constraint is fulfilled:

$$\underbrace{\dots + 0.1x^2y^2 - x^2 + 0.2x^{1.5}y^{0.5} - 1.2xy - 2x^{0.5}y^2}_{= -2.142, \text{ when } x=1, y=1.50} \leq 0$$

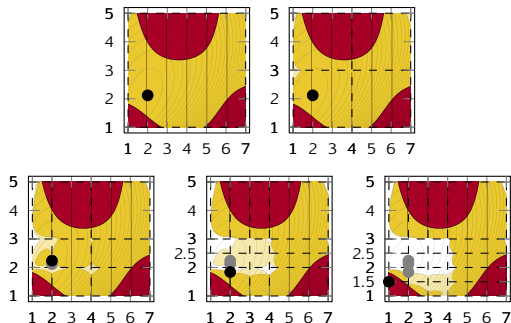
- ▶ Globally optimal solution to the nonconvex problem!



## Illustration of the convex underestimation



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Iter.	Obj. value	x	y	Constraint
1	9.97	2	2.12	1.996
2	9.97	2	2.12	1.995
3	10.00	2	2.24	2.195
4	10.14	2	1.84	1.377
5	10.92	1	1.50	-2.142



## Final remarks

- ▶ The SGO-algorithm is a global optimization algorithm for mixed integer signomial programming (MISP) problems.
  - ▶ Convex underestimators through single-variable transformations
  - ▶ A set of transformations is obtained by solving a MILP problem





## Final remarks

- ▶ The SGO-algorithm is a global optimization algorithm for mixed integer signomial programming (MISP) problems.
  - ▶ Convex underestimators through single-variable transformations
  - ▶ A set of transformations is obtained by solving a MILP problem
- ▶ On-going research:
  - ▶ Exclusion of unfeasible regions from the search-space.
  - ▶ Extension of the current problem-scope to also include any twice-differentiable nonconvex function



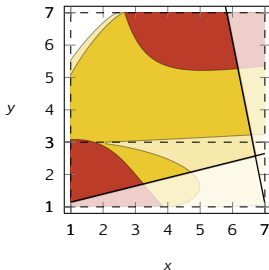
**Thank you for your attention!**

**Any questions?**



## A frequently asked question

- The following region does not seem to be convex:

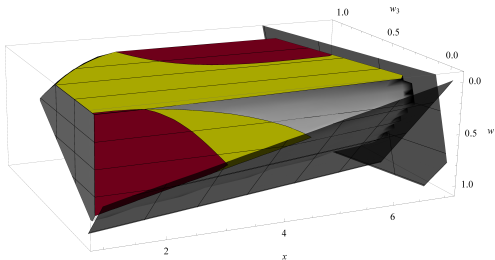
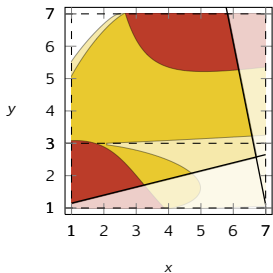


- The relaxed feasible region is convex, however, this is a projection of it for feasible values of the discrete variables defining the PLFs.



# A frequently asked question

- The region on the left does not seem to be convex:



- The “projection” (left) and an illustration of the relaxed feasible region (right).

